PURDUE **UNIVERSITY**_®

Background

The International 1/4 Scale Tractor Student Design Comp hosted by ASABE, attracts student design teams from univ around the world for a weekend long competition to decla best performing tractor. Teams must design, build, and complete pulling tractor platform starting from the provi-HP engine and rear Titan pulling tires for the target custom National Quarter Scale puller. Complications due to the CC pandemic have shifted the 2020 team's final goals and d bles. The 2020 team strives to deliver a newly generated for future students, able to go to competition, that can upon this design given a durable drivetrain and structure.

Criteria

- Robust & Durable (withstand 3000 lb. chain force)
- Manufacturable & Serviceable (80% common fasteners)
- Maneuverable (70° turn angle)
- Ergonomic controls
- (accommodate 95th percentile)

Constraints

- Weight \leq 900 lbs.
- Length \leq 96 in.
- Width \leq 72 in.
- Adequate Shielding
- Fully Customized Fr

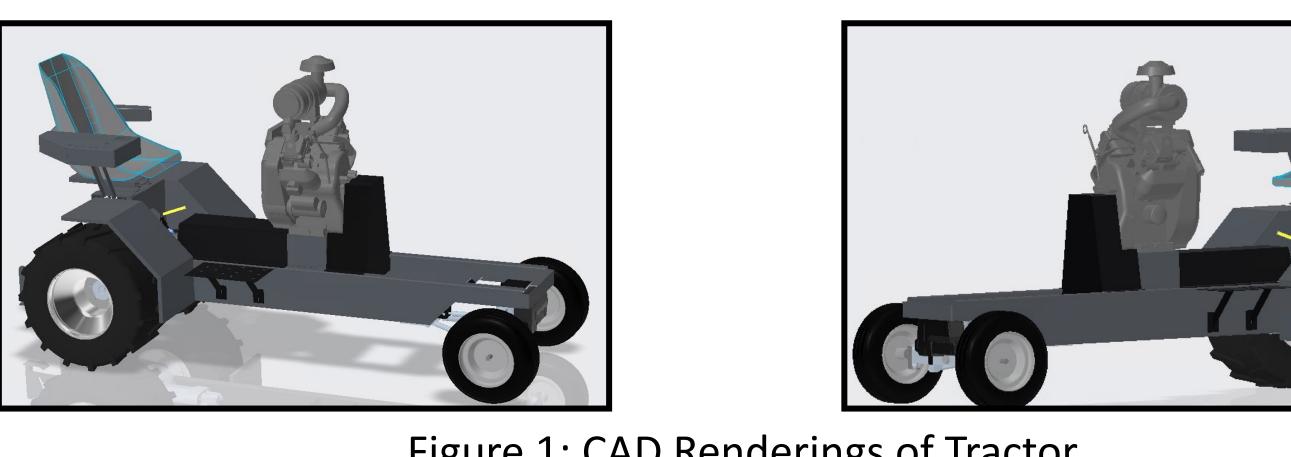


Figure 1: CAD Renderings of Tractor

Impact

- Demonstrated Purdue ABE course work and student designation capabilities for an international collegiate stage
- Executed and/or planned fully manufacturable design (Design —> Build —> Verification & Validation)
- Established technical and communication skills in a team environment
- Robust and entirely new platform for future ABE students test, iterate upon, and conquer the competition

Sponsors: John Deere Danfoss ADM **Thompson Linear**

Technical Advisor: Eric Kong

Instructors: Dr. John Evans Dr. John Lumkes

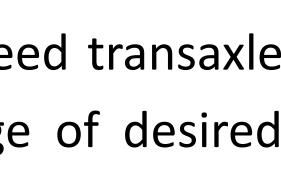


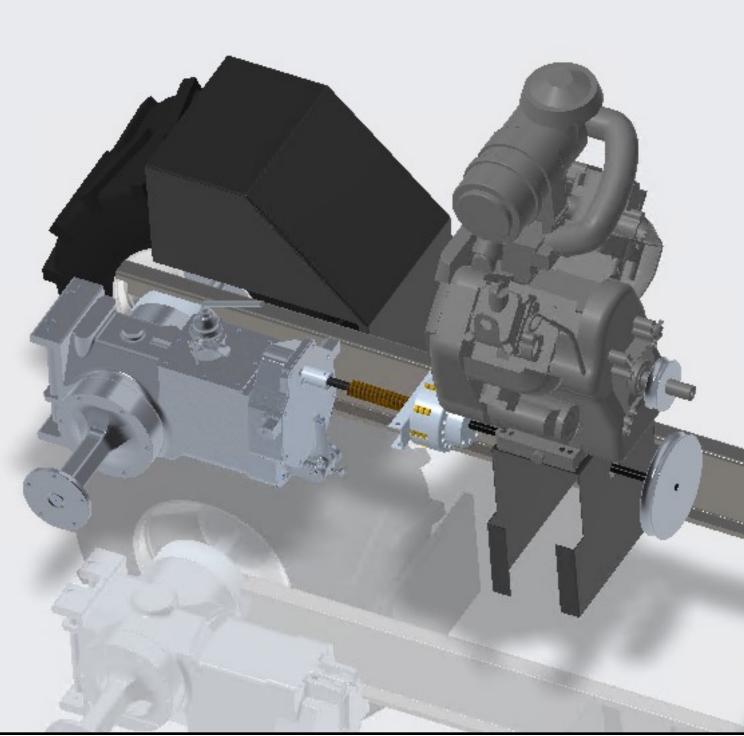
George Fontenot (AE-Machine Systems), Collin Lynch (AE-Machine Systems), Jonathan Neff (ASM), Adam Harner (ASM)

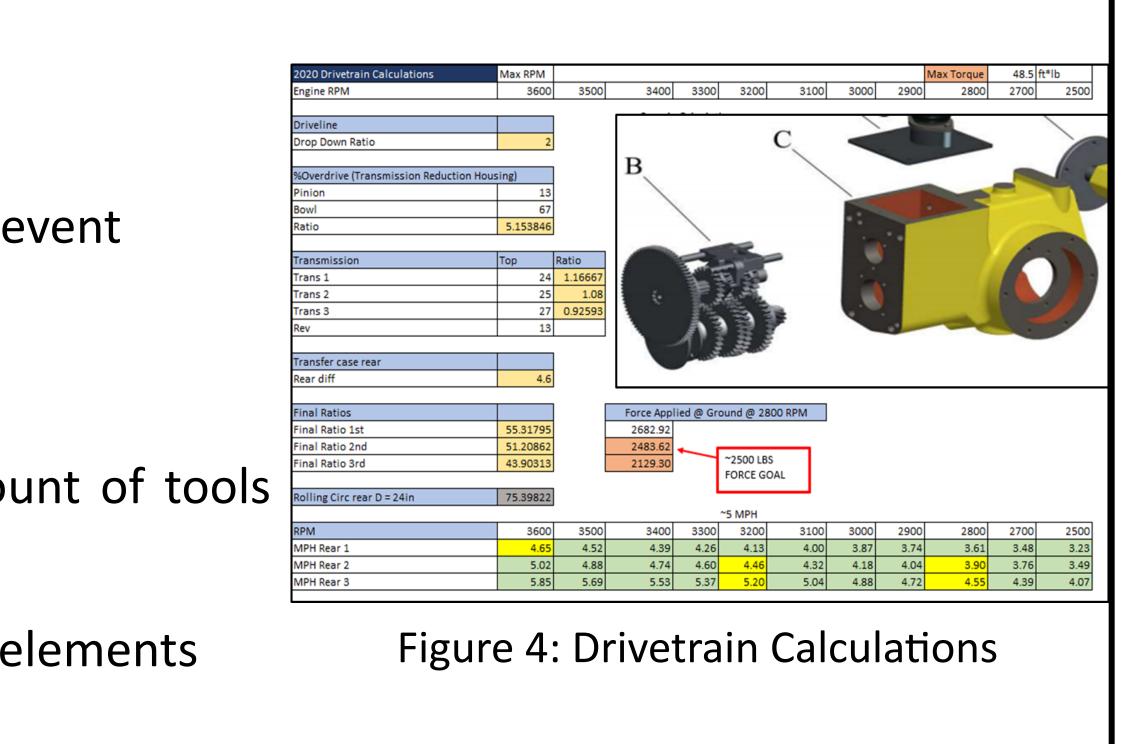
During the scope and rese	earch phase, ma	any pro	opos	ed solu	utions fo	or the c	drivetrain	configura	ation w
considered and presented	-		-					0	
•Electric 4WD					Drivetrai	n Decis	ion Matrix		
 Manual 2WD 	Drivetrain								
•Manual 4WD		Simplicity 0.09	Cost 0.07	Durability 0.17	Maneuverability 0.12	<mark>/ Traction</mark> 0.16	Controllability N 0.16	Aanufacturability 0.10	Weight 0.13
•Hydrostatic 2WD	Score Weight Electric 4wd	2.75	2.00	5.50	9.50	9.25	8.75	4.00	8.25
•Hydrostatic 4WD	Manual 2wd Manual 4wd	9.00 7.00	7.50 5.00	9.50 9.25	6.50 8.75	6.50 9.50	7.50 7.50	9.50 7.50	7.25 5.25
This process yielded Man	Hydrostatic 2wd Hydrostatic 4wd	5.75 5.00	6.25 4.00	7.75 7.75	7.50 8.75	7.00 9.00	7.00	8.50 6.75	7.00
2WD and 4WD as the mo									
2WD was selected as th					-		_		
greatest tractive pulling for	•	-	•			•	C		
	Design								
Drivotrain									
				.					
•Lightweight aluminum N	•		•						
with custom sized gear			range	of de	esired	20			The A
operating speeds and du	-	-				12			
•Vogel spline clutch and	Gates belted	sproc	ket e	engine	drop	27			
down reduction (2:1) we	re mated to a n	nain d	rives	haft		0)			
 Calculations to the botto 	om right determ	nined 3	3 forv	vard s	peeds	- Col	age -		
to maximize pulling force	e with final ratio	os fron	n 43:	1 to 5!	5:1	A.			
Frame							Figure 3	: Drivetrair	า
 C-Frame construction press 	ovides increase	d rigid	lity, r	educe	d weight	z, and e	U		
 70 inch wheel base for a 			-		C		•		
Steering				-					
	• • •		l:•		- - •				•• •
 Electronically actuated A 		ng util	ıızıng	a Dar	i⊦oss joy	зпск а	na Inom	son Linea	r actua
for accurate and respons	sive control				2020 Dri Engine Ri	vetrain Calculations PM	Max RPM 3600 3500 3400	3300 3200 3100 3000	Max Torque 0 2900 2800
Suspension					Driveline Drop Dov %Overdr Binion	vn Ratio ve (Transmission Reduction	2 Housing)	C	
 4-link airbag suspension 	for stability in c	durabi	lity e	vent	Bowl Ratio Transmis	sion	13 67 5.153846 Top Ratio		
Serviceability & Manufa	cturability				Trans 1 Trans 2 Trans 3 Rev		24 1.16667 25 1.08 27 0.92593 13		
 Simple shielding for acce 	ess to compone	nts			Transfer Rear diff Final Rat		4.6 Force App	lied @ Ground @ 2800 RPM	
 Standardized hardware 	•		ากบา	nt of	Final Rat Final Rat	io 1st io 2nd io 3rd	55.31795 2682.92 51.20862 2483.62 43.90313 2129.30	~2500 LBS FORCE GOAL	
					RPM MPH Rea MPH Rea	r 1 r 2	75.39822 3600 3500 3400 4.65 4.52 4.39 5.02 4.88 4.74	~5 MPH 3300 3200 3100 3000 4.26 4.13 4.00 3.87 4.60 4.46 4.32 4.18	0 2900 2800 7 3.74 3.61 8 4.04 3.90
needed					MPH Rea	r 3	5.85 5.69 5.53	5.37 <u>5.20</u> 5.04 4.88	8 4.72 4.55
neededMechanical drivetrain pr		_	•		⊥ -	г.	re 4: Drive		

Acknowledgements: 2020 PQS Team Members

CAPSTONE/SENIOR DESIGN EXPERIENCE 2020 Title: Purdue Quarter Scale Tractor







The rugged and versatile two-wheel drive mechanical drivetrain and structure of the 2020 Purdue Quarter Scale tractor provides a design based on proven concepts. This design will be capable of competing aggressively in pulling competitions while providing an iterative framework for completion by future teams. Other supporting design features benefit the customer with an adaptable tractor that is easily maneuverable and service friendly.

Engine Dynamometer

Competition Specific

- parking stops fully ballasted to ensure durability and make suspension adjustments

The 2020 PQS Iron Team focused on important criteria to generate a newly bred pulling platform with durable design features that will excite a future design team for completion. Careful considerations were taken when creating a final 3D model to seamlessly implement a building and testing phase by another party. The team expects the 2021 Iron Team to utilize the already purchased components, manufacture modeled components, incorporate complete data acquisition system, and validate design through harsh testing environments described.

Value Proposition

Validation and Verification Test Plans

• Ensure maximum engine torque is achieved under load • Ensure belts/sprockets are prone to failure over several runs • Monitor input and output shaft speed to ensure belt slip does not occur under heavy simulated loads

• Ensure engine exhaust meets sound requirements under 94 db • Expose tractor to rugged environments such as driving over

- Perform full competition pulls with
- practice sled to refine ballast
- placement and collect live sensory data

Data Acquisition:

- Chain Force
- Vehicle Speed
- Wheel Slip
- Driveline speed
- Engine Torque

Product Implementation